Continuous Variables Quantum Algorithm for solving Ordinary Differential Equations

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Alice Barthe



A. Barthe - QTI CERN

"Solving" ODEs

$$\dot{x} = f(x)$$

Problem 1 : Initial Value Problem

Given :
$$t > 0, f : \mathbb{R}^d \to \mathbb{R}^d, x_0 \in \mathbb{R}^d$$

Return : $x(t) \in \mathbb{R}^d$ such that :
 $x(0) = x_0$
 $\dot{x} = f(x)$



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2

Amplitude Encoded Solution Quantum Algorithms

Quantum algorithms with super-polynomial advantage return the solution as amplitude encoded state, complexity polylog(d):

$$x\rangle = \frac{1}{\|x\|_2} \sum_{k=1}^{a} x_k |k\rangle$$

For these algorithms [1] proved "non-quantumness" overheads: $O\left(e^{\delta(A)t} + \mu(A)\right)$ Spectral gap $\delta(A) = Re(\lambda)_{\max}(A) - Re(\lambda)_{\min}(A)$ Orthonormality of eigenstates : $\mu(A) = \|A^{\dagger}A - AA^{\dagger}\|^{1/2}$

[1] Dong An et al. "A theory of quantum differential equation solvers: limitations and fast-forwarding".

Koopman Von Neuman (KvN) Formalism

The framework [2] maps arbitrary classical dynamics to Hermitian dynamics in infinite Hilbert spaces.

• Wavefunction : Probability to be in a state at a given time

$$\begin{aligned} |\psi\rangle &\coloneqq \int_{-\infty}^{+\infty} \psi(x) \, |x\rangle_q dx \\ |\psi(x)|^2 &= P(x(t) = x) \end{aligned}$$

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• Hamiltonian : Time evolution = Integration of ODE $\dot{x} = f(x) \rightarrow H = f(\hat{q})\hat{p} + \hat{p}f(\hat{q})$

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[2] B. O. Koopman, "Hamiltonian Systems and Transformation in Hilbert Space"

Quantum Algorithms based on KvN

Different strategies to reduce infinite to **finite Hilbert spaces** :

• Truncation the Fock space [3]







[3] A. Engel et al, "Linear embedding of nonlinear dynamical systems and prospects for efficient quantum algorithms"[4] I. Joseph, "Koopman--von Neumann approach to quantum simulation of nonlinear classical dynamics"

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Continuous Variables Quantum Algorithm

Set of universal CV gates in the infinite Hilbert space



What if we assume perfect universal CV Quantum Computation ?





Initial State, Accuracy, Chaos and Squeezing

Goal : Solve the IVP with a given accuracy ϵ .

IVP \rightarrow **position eigenstate**, which is a **non-physical** state "approximated" by **squeezing** the state vacuum with std $\sigma_0 = e^{-r}$

Given an upper bound on the Lyapunov exponent λ



$$\partial_t d = \lambda$$

 $d(t) = e^{\lambda t} d_0$

The std of the final state $\sigma_f < \sigma_0 e^{\lambda t}$

Required initial squeezing power $r > \lambda t + \log(\epsilon)$

NB : For non-linear dynamics, may be a biased estimator



Time Evolution, and Non-Gaussian Gates

$$f(x) = \sum_{k=0}^{K} a_k x^k \to H = \sum_{k=0}^{K} a_k \{p, q^k\}$$

- Non-Linear ODE \rightarrow Non-Gaussian Gates
- Trotterization: explicit procedure to compute gate sequence for one-dimensional polynomial ODE of degree K
- Preliminary scaling : ~ $t 4^{K}$





Initial Distribution Problem : Turning a bug into a feature

Problem 2 : Initial **Distribution** Problem

Given :
$$t > 0, f : \mathbb{R}^d \to \mathbb{R}^d, p_0 : \mathbb{R}^d \to [0,1]$$

Return : $p_t : \mathbb{R}^d \to [0,1]$, such that :
 $\forall x, P(x(0) = x) = p_0(x)$
 $\dot{x} = f(x)$
 $\forall x, P(x(t) = x) = p_t(x)$

- Could be used to estimate Lyapunov exponents ?
- Could be used to characterize attractors ?



Thank you

Authors : Alice Barthe, Michele Grossi, Jordi Tura, Vedran Dunjko

Questions ?



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